

Temperature Fiber Sensors Based on Mach–Zehnder Interferometer With Sturdy Structure

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Abstract—This paper presents a highly sensitive and in-line temperature fiber sensor based on Mach–Zehnder interferometer with material overlay. The sensor is constructed using a section of single-mode fiber sandwiched between a no-core fiber and a waist-enlarged taper and immersed in a material with high thermo-optic coefficient. The experimental results indicated that a high temperature sensitivity of $0.825 \text{ nm}/^\circ\text{C}$ was accomplished for surrounding material with the refractive index of ~ 1.45 . The proposed sensor has numerous merits of in-line applications, high sensitivity, easy fabrication, simple structure, compact size, and furthermore, the structure is sturdy due to its high mechanical strength.

Index Terms—Fiber taper, interferometers, Mach-Zehnder interferometers, optical fiber sensors, temperature sensors.

I. INTRODUCTION

OPTICAL fiber sensors have many advantages, such as small size, fast response, corrosion resistance, and immunity to electromagnetic interference, so have been well developed and studied in various sensing application such as refractive index (RI) [1]–[4], temperature [5]–[9], strain [4], displacement [10], curvature [11], humidity [12], liquid level [13], directional tilt [14], etc.

Numerous structures of optical fiber sensors have been proposed using various techniques, the all-fiber Mach-Zehnder interferometers (MZI) have been intensively studied, due to their advantages such as no couplers required, high sensitivity, applicability for remote sensing and ease of fabrication. In terms of temperature measurement many types of MZI have been constructed including liquid-sealed S fiber taper [5], adding a taper to a single mode-multimode-single mode fiber (SMS) [6], photonic crystal fiber [7], fs-laser make inner air cavity [9], using S fiber taper in fiber bragg grating [15]. However, these sensors have some disadvantages of fragile structure, complicated fabrication, or expensive cost, etc.

Waist-enlarged taper (WET) have attracted substantial attention recently due to their advantages such as easy fabrication, tough structure. Many structures of sensors with WET have

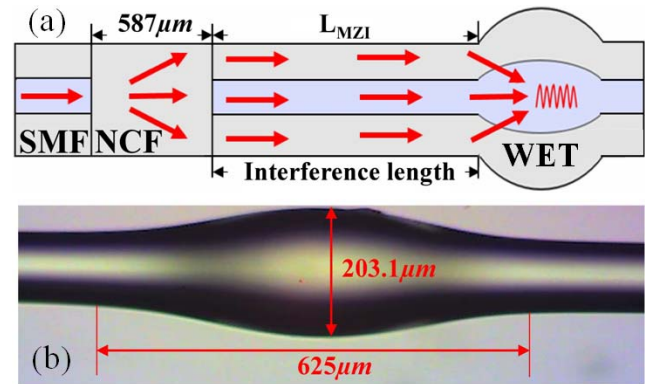


Fig. 1. (a) Configuration of the proposed MZI. (b) Microscope photograph of the WET.

been proposed, such as concatenated taper and WET for RI sensing applications [2], multimode fiber core sandwiched between two WETs [3], two peanut-shape structures [16].

Fiber-based temperature sensors typically have a low temperature sensitivity because silica fiber has an extremely low thermal expansion coefficient ($\text{TEC} = +5.5 \times 10^{-7} \text{ }^\circ\text{C}^{-1}$) and thermo-optic coefficient ($\text{TOC} = +5 \times 10^{-6} \text{ }^\circ\text{C}^{-1}$). In this paper, we present a temperature sensor based on MZI, surrounding the sensor with a high TOC material ($\text{TOC} = -3.74 \times 10^{-4} \text{ }^\circ\text{C}^{-1}$) for enhancing sensitivity. The sensor is constructed by using a piece of single mode fiber (SMF) sandwiched between a no-core fiber (NCF) and a WET. The structure has higher mechanical strength than an ordinary taper structure. For surrounding oil with a RI of 1.45, the temperature sensitivities are $0.825 \text{ nm}/^\circ\text{C}$ and $0.240 \text{ nm}/^\circ\text{C}$ in the range of $20 \text{ }^\circ\text{C}$ to $30 \text{ }^\circ\text{C}$ and $30 \text{ }^\circ\text{C}$ to $60 \text{ }^\circ\text{C}$, respectively.

In order to easily construct a sturdy sensor, this work first adopted two simple and rigid elements, NCF and WET, as the components of the sensor. In a word, the sensor has merits of in-line applications, high sensitivity, easy fabrication, simple structure, compact size, and sturdy structure.

II. CONFIGURATION AND PRINCIPLES

Figure 1(a) presents the configuration of the proposed MZI sensor. A section of SMF (called interference SMF in this paper) with a length of L_{MZI} , which is so-called interference length, is sandwiched between a NCF and a WET. A light beam from the lead-in SMF is split into the core and cladding modes at the interface between the lead-in SMF and NCF, the core and cladding modes propagate through the NCF, and inject into the interference SMF. By the WET, some cladding

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modes are coupled into the core, and unite with the core mode. Finally, the united beam outputs through a lead-out SMF.

As the core and cladding modes pass through the interference SMF, phase differences between the core and cladding modes are introduced, thus the united beam brings about interference and propagates to the output. The optical phase difference between the core and m-th order cladding mode after propagating through the length L_{MZI} of the interference SMF can be written as

$$\phi_m = \frac{2\pi}{\lambda}(n_{eff}^{co} - n_{eff}^{cl,m})L_{MZI} = \frac{2\pi}{\lambda}\Delta n_{eff}^m L_{MZI}, \quad (1)$$

where λ represents wavelength, n_{eff}^{co} and $n_{eff}^{cl,m}$ are the effective indices of the fundamental core mode and the coupling cladding mode of m-th order, respectively.

The length (L_{NCF}) and diameter of the NCF are $587 \mu\text{m}$ and $125 \mu\text{m}$, respectively. Figure 1(b) shows the microscope photograph of the WET, the length and the diameter at waist are about $625.0 \mu\text{m}$ and $203.1 \mu\text{m}$, respectively. For fabricating the WET, an electrical arc method was employed by using Ericsson FSU-975 commercial fusion splicer. A user-defined fiber taper program revised from the original ‘‘SMF taper program’’ of the fusion splicer was created firstly. The specific fabrication process can be found in [17]. The pre-fusion time and pre-fusion current are kept in default. The parameters of the overlap, the discharge current and the fusion time are set as $49.9 \mu\text{m}$, 14 mA , and 6 sec , respectively, for fusion splicing. After heating by the pre-fusion process, the fiber is softened. The SMF was then compressed simultaneously when the arc was discharging, thus the WET shown in Fig. 1(b) was formed. The parameters set for each splicing are identical; this will result in a same geometrical shape of the WETs. On the other hand, the NCF can be cut using a high precision cleaver. Therefore, the reproducibility of the proposed sensor could be ensured.

In this work, the L_{NCF} was pre-estimated by using the beam propagation method (BPM). As shown in Fig. 2(a), the simulated fiber combines a section of lead-in SMF and NCF with lengths of $100 \mu\text{m}$ and $900 \mu\text{m}$, respectively. A light beam from the lead-in SMF spreads out in the NCF and forms self-imaging [18] at periodic intervals along the NCF. The field pattern at the distance of $1000 \mu\text{m}$ ($L_{NCF}=900 \mu\text{m}$), which is displaced in Fig. 2(b), declares a fact that the core mode from the lead-in SMF is almost vanished due to the effect of multimode interference (MMI). On the contrary, for a short propagation distance of $300 \mu\text{m}$ ($L_{NCF}=200 \mu\text{m}$) as shown in Fig. 2(d), the spread of the field is not enough to result abundant cladding modes. According to interference principle, to achieve a high extinction ratio modal interference, the intensities of the two interference modes must be nearly identical. The cases of Fig. 2(b) and 2(d) violate this principle. The field pattern of $L_{NCF}=500 \mu\text{m}$ shown in Fig. 2(c) indicates a happy medium for interference. The appropriate L_{NCF} is about $500 \mu\text{m} \sim 600 \mu\text{m}$ in our experience. For shorter L_{NCF} , the intensity of the core mode is much higher than that of cladding mode. For larger L_{NCF} , the MMI effect governs the intensity distinction between the core and cladding modes. This brings about an uncertain situation.

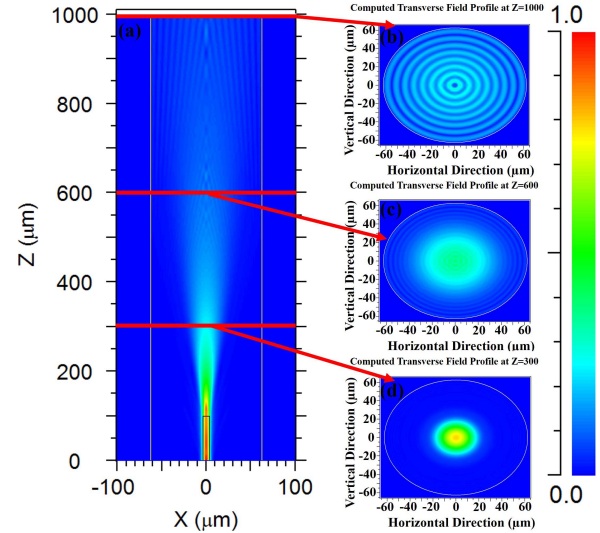


Fig. 2. (a) Simulated field propagates in a combination of lead-in SMF ($Z=0 \sim 100 \mu\text{m}$) and NCF ($Z=100 \sim 1000 \mu\text{m}$), and cross-sectional views of the field patterns at the distances of (b) $1000 \mu\text{m}$, (c) $600 \mu\text{m}$, and (d) $300 \mu\text{m}$.

The light spread in the NCF is then injected into the interference SMF. The fields of the light propagated in the interference SMF were simulated by using the BPM again, and the results are shown in Fig. 3. The simulated fiber in the figure is composed by sandwiching a section of NCF between the lead-in SMF and the interference SMF, the lengths of lead-in SMF, NCF, and interference SMF are $100 \mu\text{m}$, $587 \mu\text{m}$, and 1.2 cm , respectively. Figure 3(a)-(d) display the fields propagate in the fiber surrounded by the material with RI (n_D) of 1.33 (Fig. 3(a)), 1.39 (Fig. 3(b)), 1.44 (Fig. 3(c)), and 1.45 (Fig. 3(d)), respectively. Figure 3(e)-(h) demonstrate the cross-sectional views of the field patterns at the distances of $Z=1310 \mu\text{m}$ for the surrounding materials with $n_D=1.33$ (Fig. 3(e)), 1.39 (Fig. 3(f)), 1.44 (Fig. 3(g)), and 1.45 (Fig. 3(h)), respectively. The contour levels shown in the inset represent the powers normalized with launched into the lead-in SMF. As shown in the figures, as expectancy, abundant cladding modes are produced in the cladding for each surrounding materials, this can be ascribed to the appropriate length of NCF. Furthermore, for $n_D=1.44$ and 1.45 , the cladding modes stretch out their mode field into the surrounding due to the RI of the surrounding approximates to that of the cladding. This phenomenon is especially severe for the case of $n_D=1.45$.

Figure 4 indicates the experimental setup of the proposed MZI sensor. Light from a wide band light source (WBL) with a wavelength range of $1250 \sim 1650 \text{ nm}$ is launched into the MZI, and transmission spectra are detected by an optical spectrum analyzer (OSA). The MZI is laid on a U-groove, which is used to contain the surrounding liquid, the Cargille index oil with a high TOC of $-3.74 \times 10^{-4} \text{ }^\circ\text{C}^{-1}$, and fixed two ends by fixed stages to avoid the influence of bending interference. The applied temperature T ($^\circ\text{C}$) is controlled by a TE cooler from $20 \text{ }^\circ\text{C}$ to $60 \text{ }^\circ\text{C}$ to measure the spectral variation with T-changing.

Figure 5 shows the transmission spectra of the MZI structures without material overlay, i.e. in air, in room temperature.

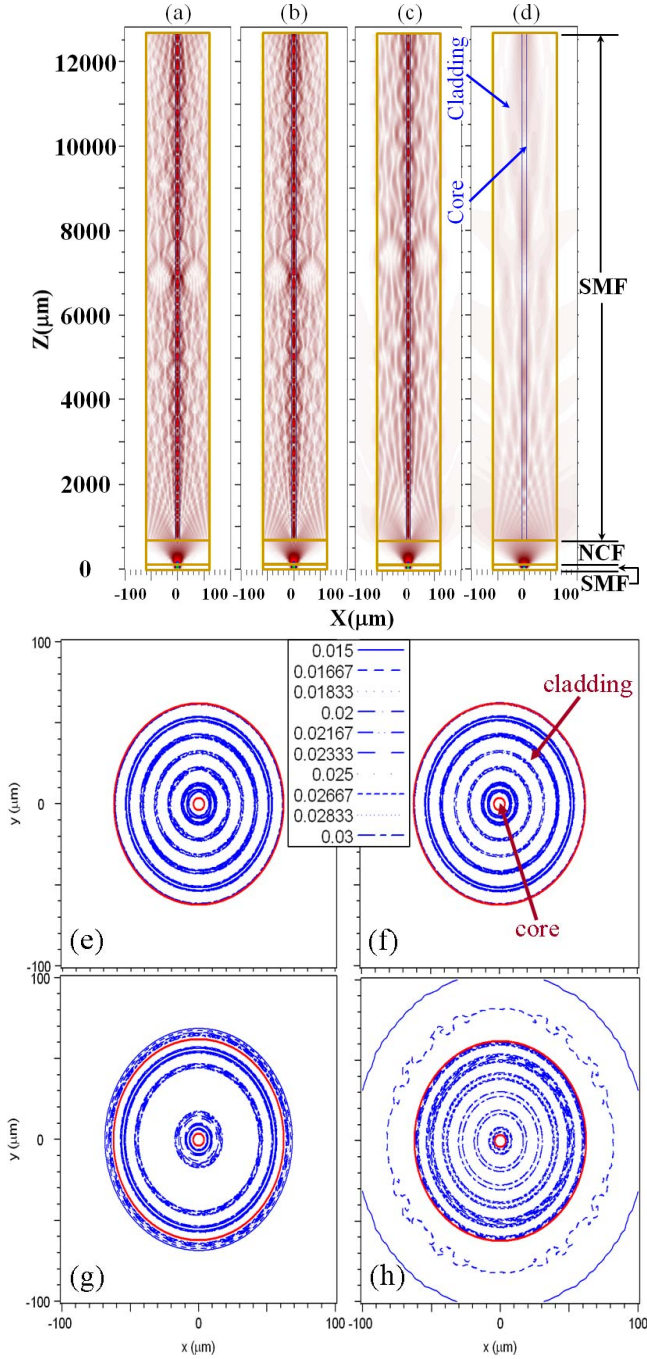


Fig. 3. Simulated field propagated in a combination of SMF-NCF-SMF immersed in the material with the n_D of (a) 1.33, (b) 1.39, (c) 1.44, (d) 1.45, and cross-sectional views of the field patterns at the distances of $Z=1310 \mu\text{m}$ for the surrounding with the n_D of (e) 1.33, (f) 1.39, (g) 1.44, (h) 1.45. The contour levels in the inset represent the normalized powers.

As shown in the figure, the loss is about 10 dB for the three cases due to beam-split in the NCF. The structure without WET reveals no interference because the cladding modes can't couple into the core without WET, and can't interfere with the core mode. For the structures with WET (two cases of $L_{MZI}=1 \text{ cm}$ and 1.2 cm), a cladding mode and the core mode are assembled at the WET and result interference.

The wavelength of spectral minima λ_{\min}^m can be deduced by substituting the condition of interference minima

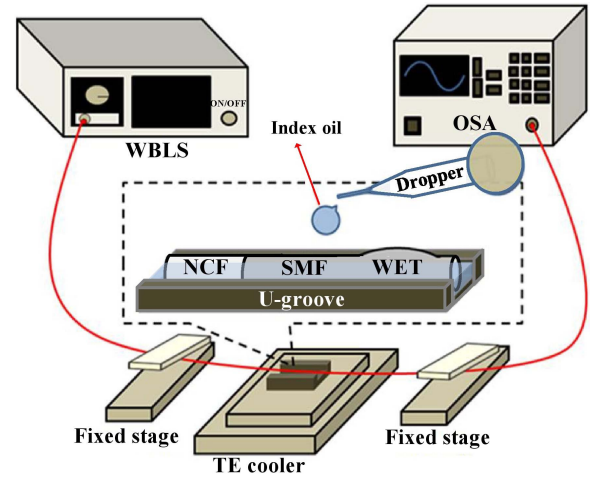


Fig. 4. Experimental setup for measuring the temperature by the proposed MZI sensor.

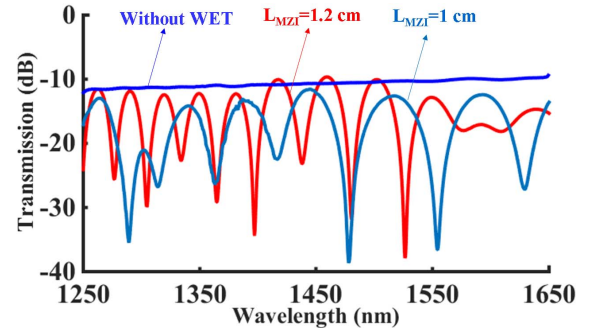


Fig. 5. Transmission spectra of the MZI structures without material overlay (in air) in room temperature.

$\phi_m=(2n+1)\pi$, where n is an integer, into Eq. (1):

$$\lambda_{\min}^m = \frac{2}{2n+1} \Delta n_{eff}^m L_{MZI}. \quad (2)$$

In addition, from Eq. (1), the free space range (FSR), the wavelength separation between two interference minima, can be approximated as:

$$FSR \approx \frac{\lambda^2}{\Delta n_{eff}^m L_{MZI}}. \quad (3)$$

As shown in Fig. 5, a larger L_{MZI} results in a smaller FSR , this can be clarified by Eq. (3).

III. EXPERIMENTAL RESULTS AND DISCUSSION

Figure 6 shows the experimental spectra of the proposed MZI temperature sensor with $L_{MZI}=1.2 \text{ cm}$ overlaid with materials of various RI values. At lower surrounding RI, the MZI has a very poor sensitivity to external temperature. Owing to the greater parts of cladding modes are confined in the cladding, as shown in Fig. 3, which is formed with pure silica with an extremely low TOC. Therefore, the variations in Δn_{eff}^m with temperature are smaller. The MZI immersed in a surrounding with the RI of $n_D=1.45$ is most sensitive to temperature. This occurs because, at $n_D=1.45$, the cladding

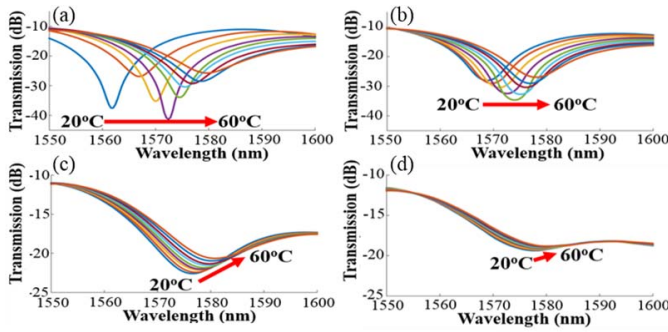


Fig. 6. Experimental transmission spectra of the proposed MZI temperature sensor with various T for material surroundings with indices of (a) $n_D=1.45$, (b) $n_D=1.44$, (c) $n_D=1.39$, and (d) $n_D = 1.33$. $L_{NCF}=587 \mu\text{m}$, $L_{MZI}=1.2 \text{ cm}$.

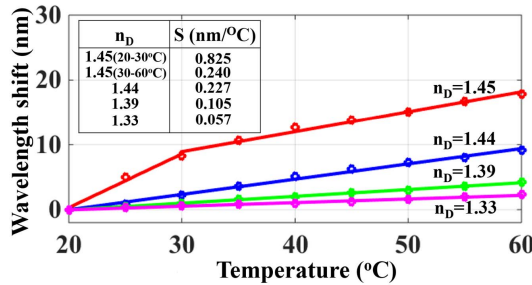


Fig. 7. Sensitivities of shifts in wavelengths of MZIs with surroundings of various RI values. Inset shows the corresponding sensitivity of the used index oil. $L_{NCF}=587 \mu\text{m}$, $L_{MZI}=1.2 \text{ cm}$.

modes greatly stretch out their mode fields into the surrounding which has a high TOC, as shown in Fig. 3, thus the Δn_{eff}^m is influenced by the surrounding severely.

As shown in the figures, the spectra move to longer wavelength with temperature increasing. This phenomenon can be explained as follows: as temperature increase, the environmental refractive index decreases due to the negative TOC of the surrounding, thus the effective index of the cladding modes may decrease and that of the core mode does not change much, and Δn_{eff}^m will increase accordingly. Consequently, the spectra should shift to longer wavelength according to Eq. (2).

Figure 7 shows the fitted linear response of the sensitivities for various RIs of the material and the inset lists the relation between n_D and sensitivity in nm/°C. Here, the n_D values of the used Cargille index oil are measured at 25°C, Sodium D Line, and $\lambda = 589.3 \text{ nm}$. The results reveal a highly linear response to temperature. Furthermore, the sensor has high sensitivity when the RI of the surrounding material approaches that of the fiber ($n_D=1.45$). Because the cladding modes, as mentioned above, strongly stretch out into the surroundings with a TOC much higher than silica, thus the Δn_{eff}^m varies with great sensitivity for T-changing. Figure 7 appears saturation of sensitivity response for $n_D=1.45$ in the temperature range of $T > 30^\circ\text{C}$, this can be explained as follows. The surrounding material drops its RI for higher temperature, and the lower RI causes the cladding modes shrink their mode fields back to the fiber and induces lower sensitivity as mentioned above. Therefore, higher temperature reduces

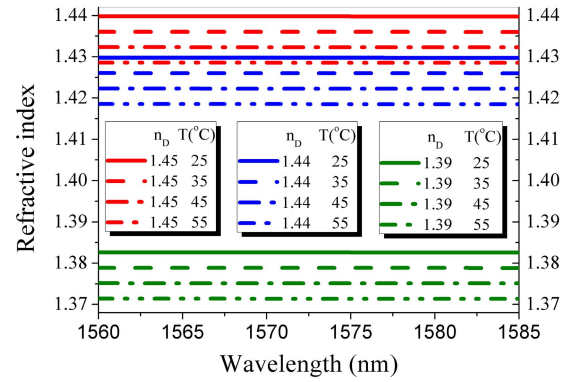


Fig. 8. Relationship between the RIs of the surrounding materials and wavelengths at various temperatures for the proposed MZI. $L_{NCF}=587 \mu\text{m}$, $L_{MZI}=1.2 \text{ cm}$.

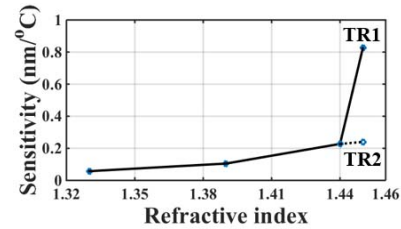


Fig. 9. Dependence of temperature sensitivity on the RI of surrounding material. $L_{NCF}=587 \mu\text{m}$, $L_{MZI}=1.2 \text{ cm}$. (for $n_D=1.45$, TR1: T=20-30°C; TR2: T=30-60°C.)

the sensitivity for the case of $n_D=1.45$. By respectively using the Cauchy equations and TOC of the Cargille index oils of $n_D=1.45$, 1.44 and 1.39, the relationship between the RIs, at the temperatures of 25, 35, 45, and 55°C, of the surrounding materials and wavelengths for the proposed MZI is shown in Fig. 8. The Cauchy equation is given by

$$RI(\lambda) = A + \frac{B}{\lambda^2} + \frac{C}{\lambda^4} \quad (4)$$

where λ is the vacuum wavelength in angstroms, A, B, and C are the Cauchy coefficients which vary with different materials. As shown in the figure, the refractive indices of the surrounding materials appear slightly downward sloping curves toward longer wavelength due to Eq. (4) and obviously decrease with temperature increasing caused by the negative TOC. It is obvious, for a higher temperature, the RIs of $n_D=1.45$ drop into the “RI range” of $n_D=1.44$. Therefore, as shown in the inset of Fig. 7, the sensitivity for $n_D=1.45$ at higher temperatures approaches to that of $n_D=1.44$.

Figure 9 demonstrates the dependence of temperature sensitivity on the RI of surrounding material. In the figure, for $n_D=1.45$, TR1 and TR2 represent different temperature range of 20 °C to 30 °C, and 30 °C to 60 °C, respectively. Comparing the temperature sensitivity for various surrounding RI values (n_D), TR1 of $n_D=1.45$ exhibits an extremely high sensitivity ($S=0.825 \text{ nm/}^\circ\text{C}$). Comparatively, TR2 of $n_D=1.45$ reveals a lower sensitivity ($S=0.240 \text{ nm/}^\circ\text{C}$) due to the saturation condition mentioned above. Even so, the sensitivities of the proposed sensor with $n_D=1.45$ are much higher than the previous works. For the surrounding materials

TABLE I
PROPOSED SENSOR IS COMPARED IN TERMS OF SENSITIVITY
AND TEMPERATURE RANGE WITH OTHER FIBER OPTIC
TEMPERATURE SENSORS

Ref.	Structure (Type)	Sensitivity (pm/°C)	Temperature range
The work	NCF-SMF-WET with Material Overlay (MZI)	825	20 °C to 30 °C
		240	30 °C to 60 °C
[5]	Liquid-Sealed S-Taper (MZI)	-1403	20 °C to 50 °C
[6]	MMF-SMF-Taper (MZI)	85.8	100 °C to 400 °C
		128.6	400 °C to 850 °C
[7]	PCF with Material Overlay (MZI)	-920	25 °C to 50 °C
[8]	Liquid filled PCF (MI)	5400	25 °C to 30 °C
[9]	Air cavity in SMF (MZI)	43.2	27 °C to 1000 °C
[15]	S-Taper in FBG (MZI&FBG)	14.71	28 °C to 95 °C

* MZI: Mach-Zehnder interferometer
MI: Michelson interferometer
FBG: Fiber Bragg Grating

with $n_D < 1.45$, the temperature sensitivities are even lower than the cases of TR1 and TR2 of $n_D = 1.45$.

Table I shows comparisons for the sensitivities and temperature ranges of the proposed sensor with other fiber optic temperature sensors. In overview, using a high TOC material in the device can enhance the sensitivity of the sensor; nevertheless, that will reduce the wavelength range in use. The using of taper or S-taper is fragile, that of PCF is more expensive, and some structures are complicated in fabrication. The proposed sensor has advantages of high sensitivity, easy fabrication, simple structure, and sturdy structure as mentioned above. Every sensor has its strong and weak points, one can select a suitable structure depend on the application.

IV. CONCLUSION

A simple in-line temperature fiber sensor based on MZI with high sensitivity is proposed. Immersing the proposed NCF-SMF-WET structure in a high TOC material with a RI of 1.45 had demonstrated that high temperature sensitivities of 0.825 nm/°C (20-30 °C) and 0.240 nm/°C (30-60 °C) were accomplished. The sensor has merits of in-line applications, high sensitivity, easy fabrication, simple structure, compact size, and furthermore the structure is sturdy due to its high mechanical strength.

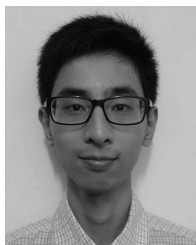
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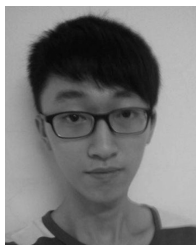
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